L Number	Hits	Search Text	DB	Time stamp
-	698	manufacturing adj cell	USPAT;	2004/09/30 07:58
			US-PGPUB	, , , , , , , , , , , , , , , , , , , ,
_	629	geometric adj description	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	10780	tree adj structure	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	5183	(tree adj structure) and database	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	4154	cost adj function	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	6874	weighted adj sum	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	292	(cost adj function) with distance	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	50513	degree adj2 freedom	USPAT;	2004/09/30 07:58
			US-PGPUB	
-	171	(degree adj2 freedom) with rotation with	USPAT;	2004/09/30 07:58
	100	orientation	US-PGPUB	5004/00/00 07 50
_	199	traveling adj salesman adj problem	USPAT;	2004/09/30 07:58
_	6323	template and robot\$	US-PGPUB	2004/00/20 07 50
	0343	cempiace and topots	USPAT; US-PGPUB	2004/09/30 07:58
_	49794	link and joint	USPAT:	2004/09/30 07:58
	43134	Tillik alid joille	US-PGPUB	2004/09/30 07:58
_	595	(template and robot\$) and (link and joint)	USPAT;	2004/09/30 07:58
	373	, (Josephane and Loboty) and (Time and Joint)	US-PGPUB	2004/09/30 07:38
_	272	sensor and ((template and robot\$) and (link	USPAT;	2004/09/30 07:58
	2,2	and joint))	US-PGPUB	2001/05/30 07.30
-	163	(sensor and ((template and robot\$) and (link	USPAT;	2004/09/30 07:58
		and joint))) and coordinate and (movement	US-PGPUB	2001,03,30 07.30
		motion)	00 10102	
-	. 60	(manufacturing adj cell) and workpiece	USPAT;	2004/09/30 07:59
			US-PGPUB	
	288	703/1.ccor.	USPAT;	2004/09/30 08:00
			US-PGPUB	
-	1	((manufacturing adj cell) and workpiece) and	USPAT;	2004/09/30 08:00
		geometric adj description	US-PGPUB	
-	5	(manufacturing adj cell) and (geometric adj	USPAT;	2004/09/30 08:00
		description)	US-PGPUB	
-	449	((tree adj structure) and database) and	USPAT;	2004/09/30 08:00
	126	joint	US-PGPUB	
-	136	703/8.ccor.	USPAT;	2004/09/30 08:00
_	95	703/7.ccor.	US-PGPUB	2004/00/20 00 00
_	95	70377.6601.	USPAT;	2004/09/30 08:00
_	12	4877940.URPN.	US-PGPUB USPAT	2004/09/20 09:00
_	16	attracting adj pairs	USPAT;	2004/09/30 08:00 2004/09/30 08:00
	10	accessing any paris	US-PGPUB	2007/03/30 08:00
_	247	703/6.ccor.	USPAT;	2004/09/30 08:00
		·	US-PGPUB	= 301, 05, 50 00.00
-	5	repelling adj pairs	USPAT;	2004/09/30 08:00
		_ <del></del>	US-PGPUB	-
-	6	("4912657"   "5586052"   "5771342"	USPAT	2004/09/30 08:00
		"5835693"   "5980084"   "6063126").PN.		
-	62	(manufacturing adj cell) and optimization	USPAT;	2004/09/30 08:00
			US-PGPUB	
-	3	("5748847"   "6031935"   "6395478").PN.	USPAT	2004/09/30 08:00
-	32	("3654615"   "4495559"   "4607339"	USPAT	2004/09/30 08:00
		"4615010"   "4931944"   "5077676"		
	*	"5134685"		
		"5159682"   "5200908"   "5218551"		
İ		"5224056"   "5225991"   "5235521"		
		"5237514"   "5308798"   "5326659"		
		"5333032"   "5339253"   "5349536"   "5359535"   "5363313"   "5388055"		
İ		"5359535"   "5363313"   "5388055"   "5402357"   "5416718"   "5432447"		
İ		"5557533"   "5563783"   "5568636"		
	ļ	"5619419"   "5636125").PN.		
_	34	value with joint with limit with within	USPAT;	2004/09/30 08:00
1		The second of th	US-PGPUB	2501/05/50 00:00
				<u> </u>

-	2	kinematic adj tree	USPAT; US-PGPUB	2004/09/30 08:00
-	33	((cost adj function) with distance) and (weighted adj sum)	USPAT; US-PGPUB	2004/09/30 08:00
-	13	igrip	USPAT; US-PGPUB	2004/09/30 08:00
-	. 1	("5043929").PN.	USPAT;	2004/09/30 08:00
-	20	robcad	US-PGPUB USPAT;	2004/09/30 08:00
-	3	((degree adj2 freedom) with rotation with	US-PGPUB USPAT;	2004/09/30 08:00
_	13	orientation) and (pair near3 point) ("3321072"   "3909600"   "3920972"	US-PGPUB USPAT	2004/09/30 08:00
		"4381608"   "4591771"   "4705451"   "4811235"   "4920500"   "5053975"   "5053976"   "5129044"   "5129045"		
_	11	"5471395").PN.   5604677.URPN.	USPAT	2004/09/30 08:00
	9	congruent with (pair near3 point)	USPAT	2004/09/30 08:00
1_	24	4891762.URPN.	USPAT	2004/09/30 08:00
-	22	(traveling adj salesman adj problem) and 3d	USPAT; US-PGPUB	2004/09/30 08:00
-	1	("6507771").PN.	USPAT; US-PGPUB	2004/09/30 08:00
-	14	("4028533"   "5233604"   "5561790"   "5675741"   "5946083"   "5991300"   "6154139"   "6195020"   "6208247"   "6311129"   "6330493"   "6341246"   "6374155"   "6408226").PN.	USPAT	2004/09/30 08:00
-	4	(("4851748") or ("4954762") or ("5357439") or ("6004016")).PN.	USPAT; US-PGPUB	2004/09/30 08:00
-	. 42	((sensor and ((template and robot\$) and (link and joint))) and coordinate and (movement motion)) and tree	USPAT; US-PGPUB	2004/09/30 08:00
	138	700/56.ccor.	USPAT; US-PGPUB	2004/09/30 08:00
-	74	700/96.ccor.	USPAT; US-PGPUB	2004/09/30 08:00
-	43	700/251.ccor.	USPAT; US-PGPUB	2004/09/30 08:00